



Improved Calibration through SMAP RFI Change Detection

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Outline



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- SMAP Error Budget
- How SMAP RFI Detection and Filtering Works
- Error Performance in Lab Environment
- Motivation
- Control Charting for Process Monitoring
- RFI Statistics
- Case #1: Kerrville, TX
- Case #2: Europe
- What's next?

Radiometer Hardware and Algorithm Have Error Budget (Margin When RFI Mitigation Succeeds)



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Error Term

Multi-look averaged TB

Current Best Estimate

Antenna Pattern Correction –
Instrument component

0.40 K

Antenna Pattern Correction –
Algorithm component

0.40 K

NE Δ T

0.45 K

Antenna Temperature
Calibration

0.44 K

RFI

0.23 K

Long Term Drift

0.2 K

Atmospheric Correction

0.04 K

RSS Total

0.90 K

Requirement

1.3 K

Margin (Unencumbered RSS)

0.93 K

Margin (Unencumbered Linear)

0.40 K

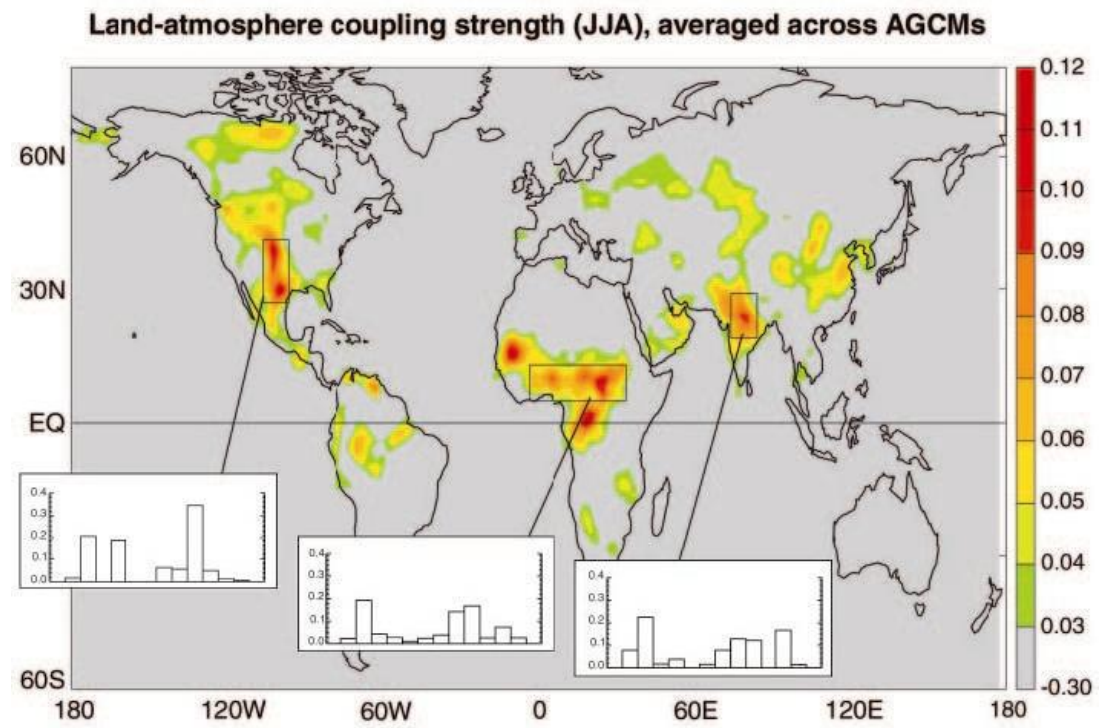
Single-look TB Performance

Assessed by Cal/Val Team for the Level 1B_TB product

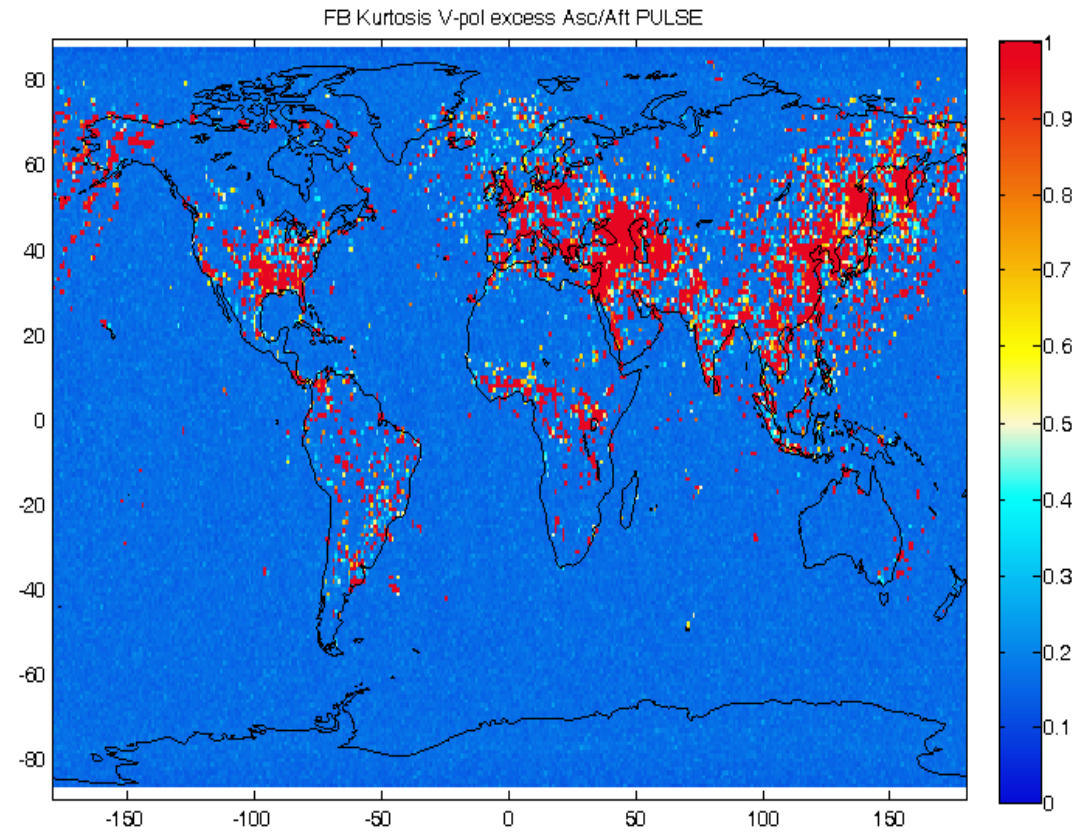
Metric	Allocation	Measured
Ocean Model RMSD (incl. NEDT)	1.4 K	1.2 K
NEDT (land)	1.6 K	1.2 K
NEDT (ocean)	1.1 K	0.9 K
Monthly Drift	0.4 K	+0.1/-0.25



Relevance



Locations where soil moisture has the greatest influence on precipitation. (Fig.17 from *SMAP Decadal Survey Workshop Report* from Koster et al. (2004) *Science*)

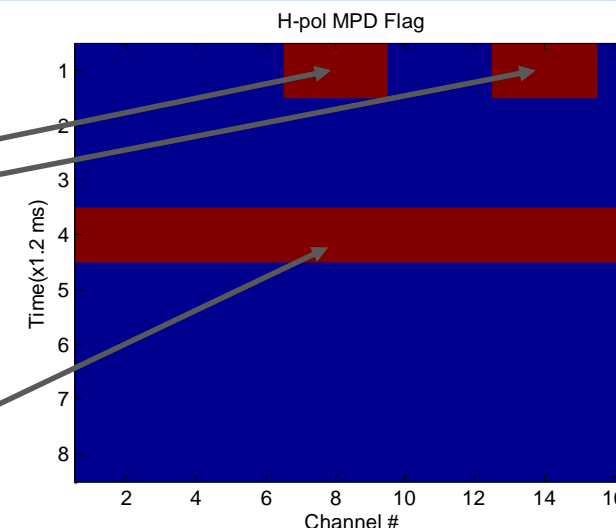
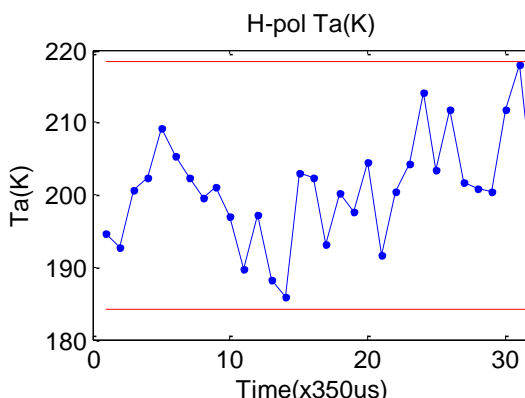
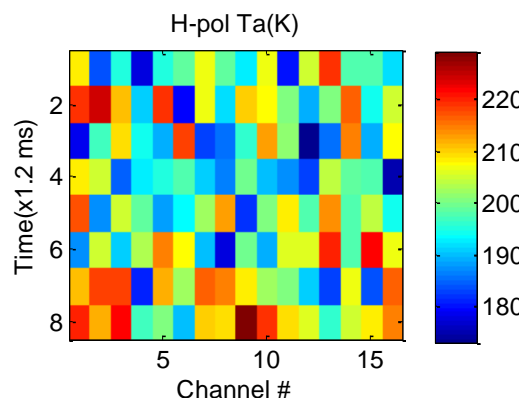
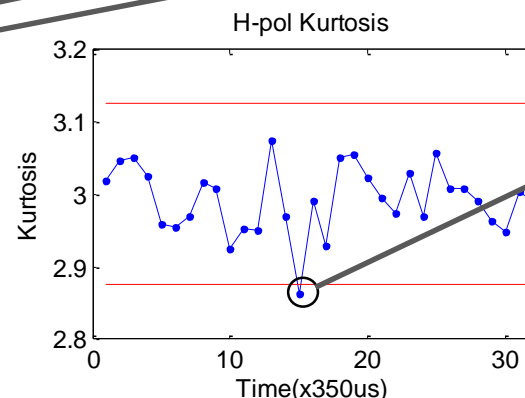
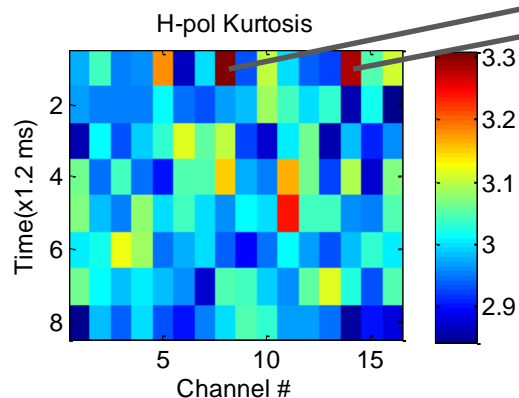


Presence of ground radar RFI indicated by kurtosis measurements.



How SMAP RFI Detection and Filtering Works

Subband detection algorithms detect and flag RFI; also flag adjacent channels



Time domain detectors detect and flag RFI; MPD flags corresponding time slice in subband data

Drop all flagged data and average remaining clean pixels of subband data to get RFI free footprint, T_A



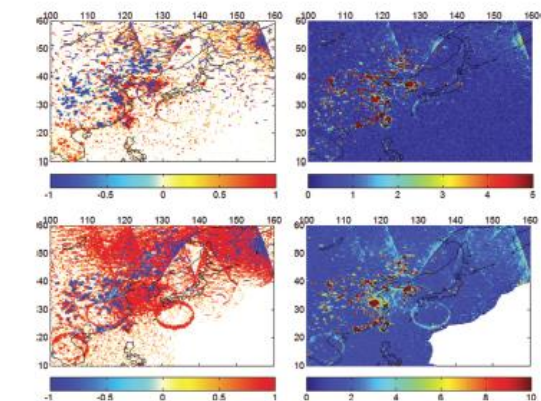
Error Performance in Lab Environment

IEEE TRANSACTIONS ON GEOSCIENCE AND REMOTE SENSING

A PUBLICATION OF THE IEEE GEOSCIENCE AND REMOTE SENSING SOCIETY



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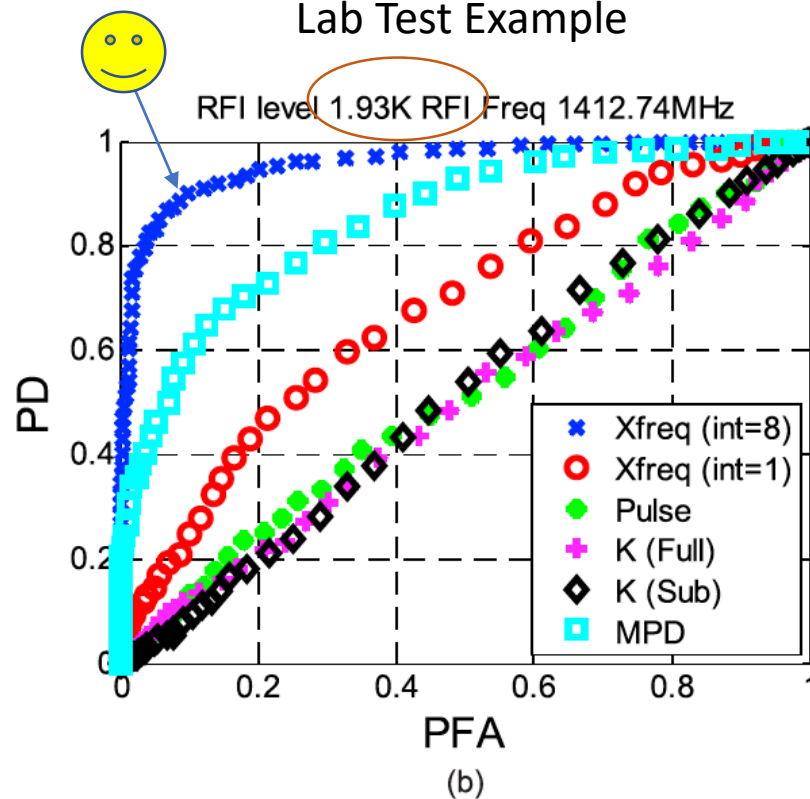


These figures show the measured RFI detection rates in East Asia and Japan, as measured by the SMAP mission 1400-1427 MHz radiometer for the period June 3, 2015 to June 9, 2015. The top two figures are ensemble RFI detection rates (left) and RFI detection rates (right) over East Asia derived from the high-resolution data stream. The bottom two figures show similar information obtained from the coarser-resolution data stream.

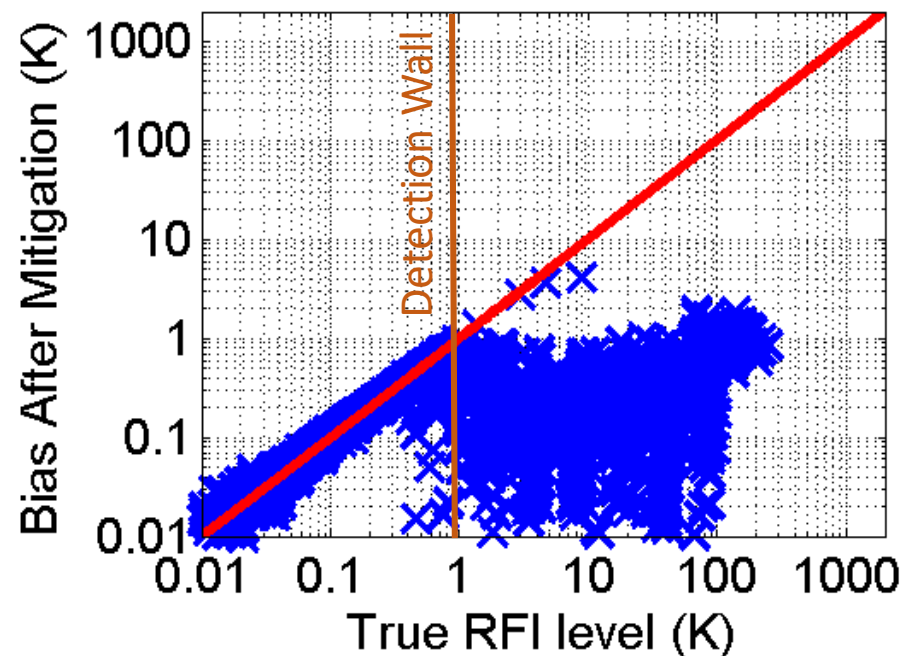


Mohammed, et al.

Low-amplitude Narrowband RFI Lab Test Example



0.23-K mean bias From J. Johnson TVAC assessment report

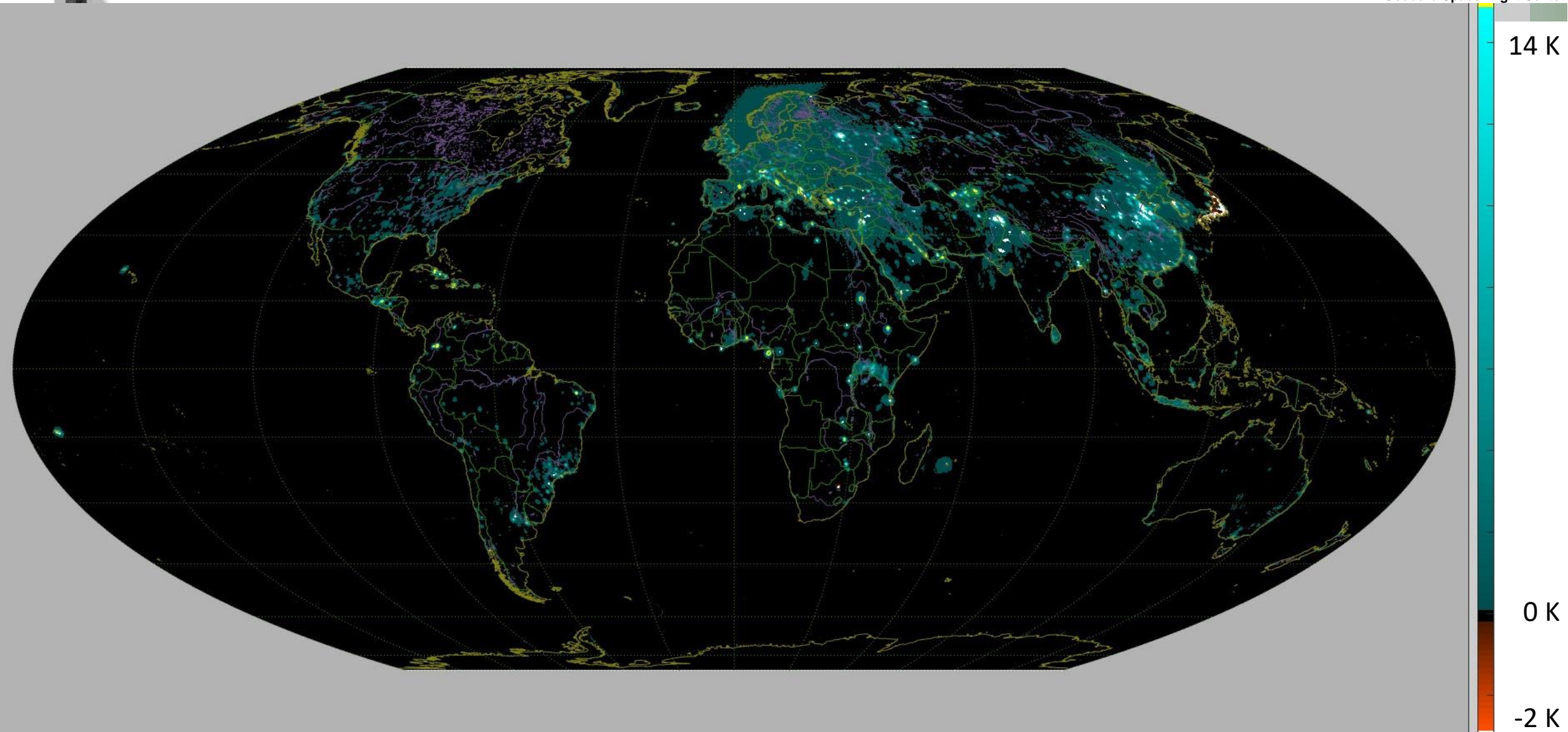




Global Time-Averaged RFI



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10/12/17

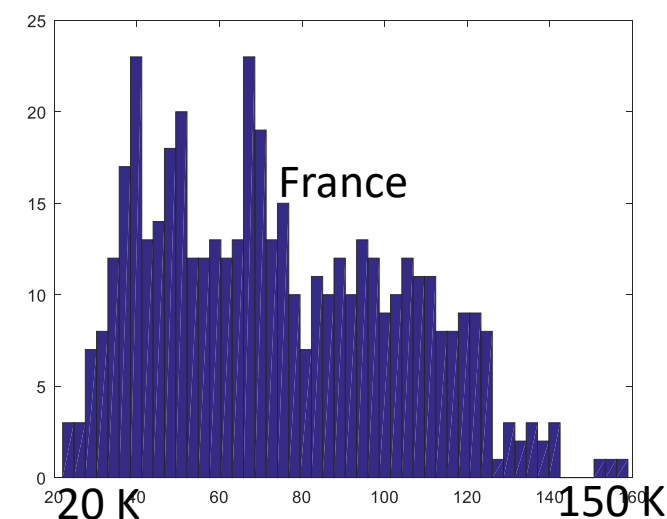
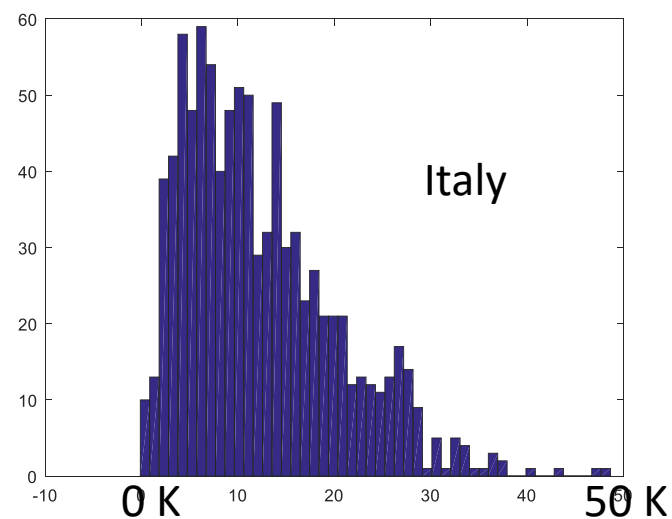
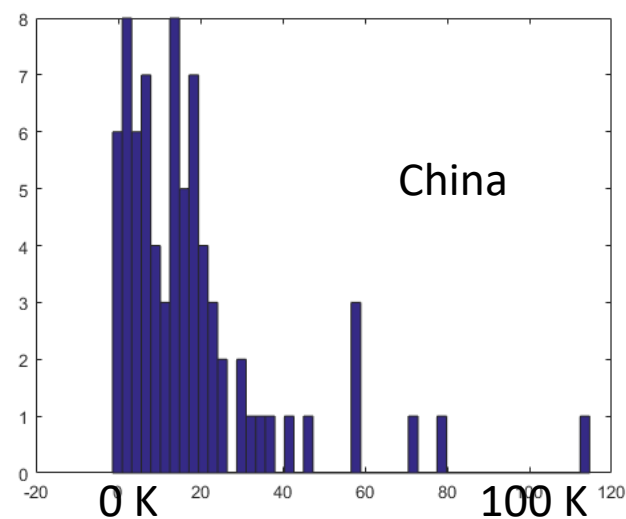
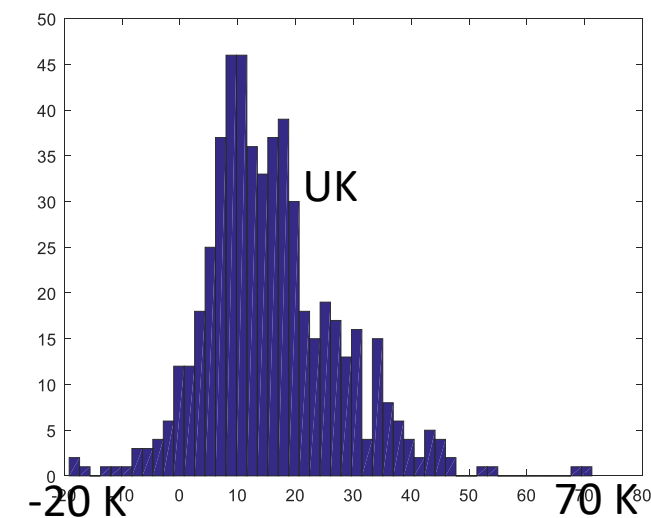
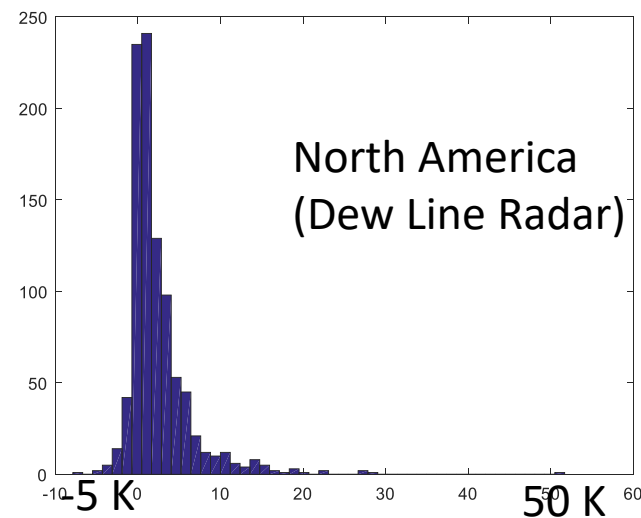
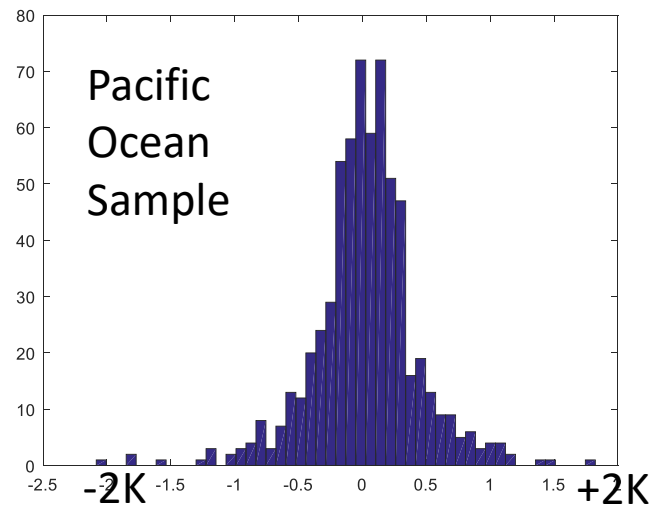
SUSMAP - Cambridge, MA



Average RFI Intensity Time Series Distributions



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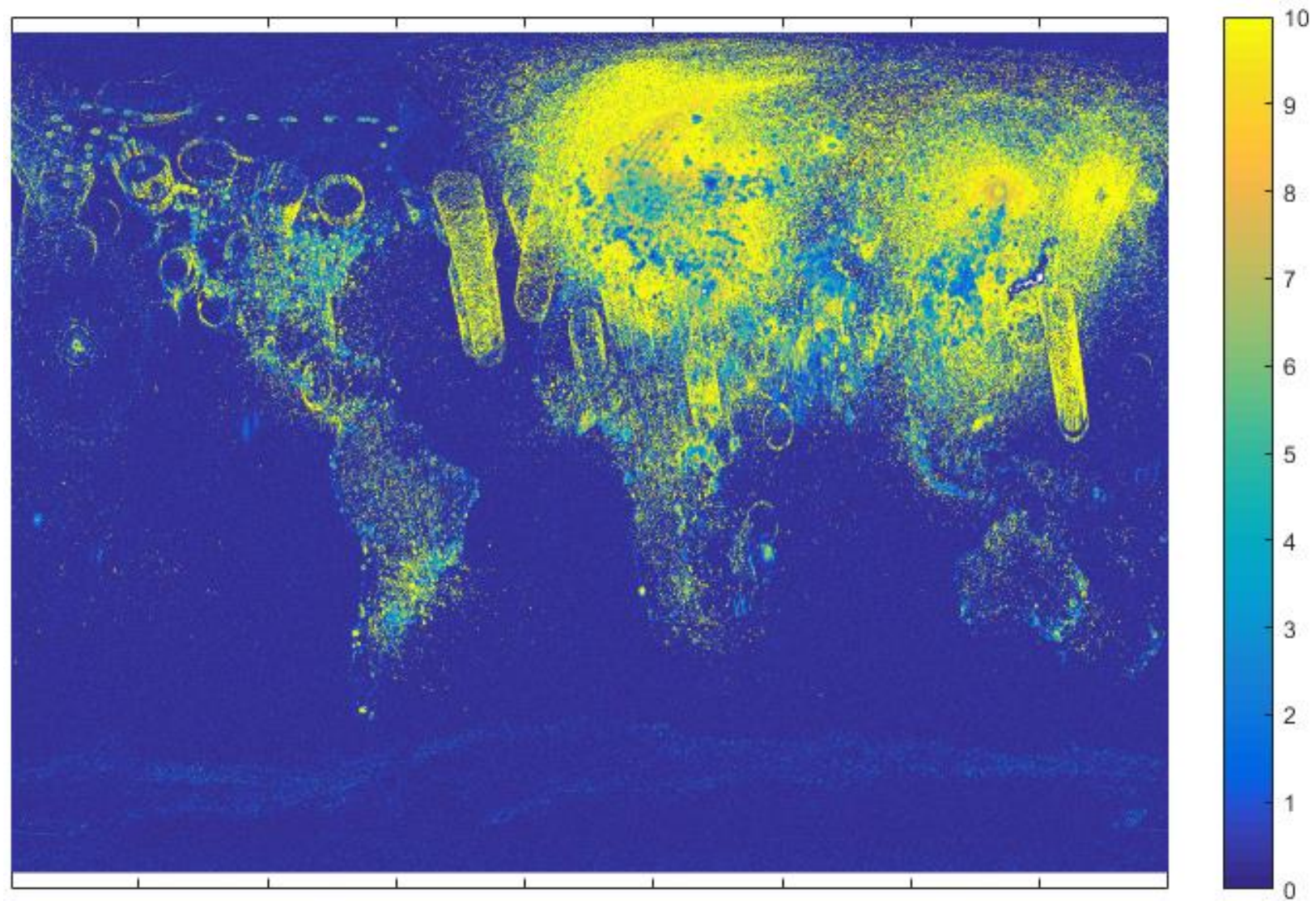
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SUSMAP - Cambridge, MA

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Time Series Skewness

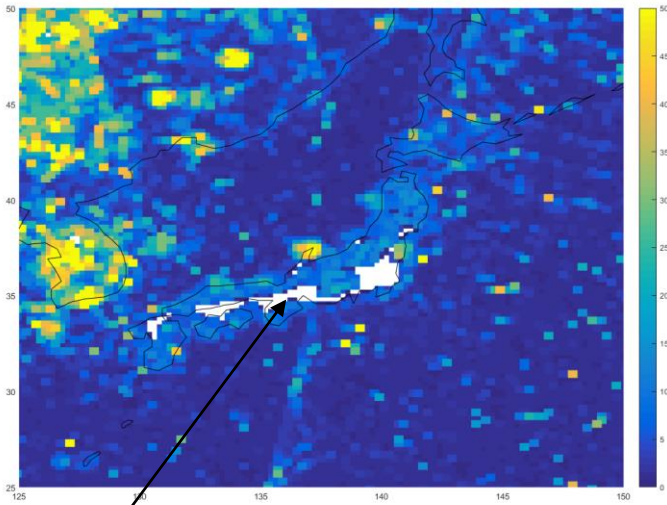




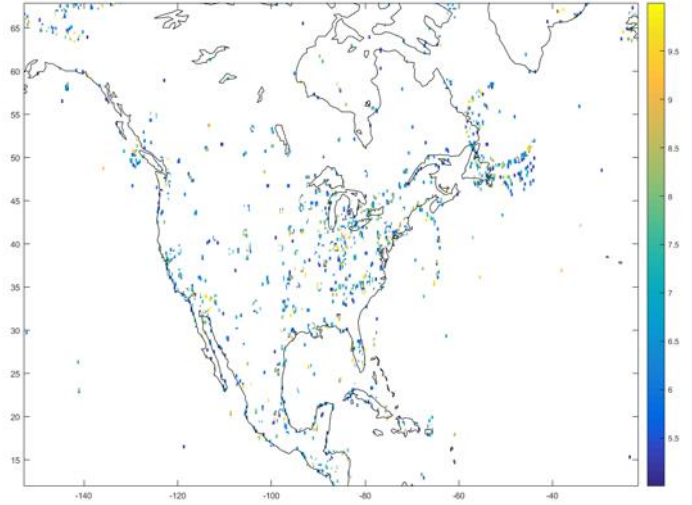
Sticky RFI: Choose Your Flavor



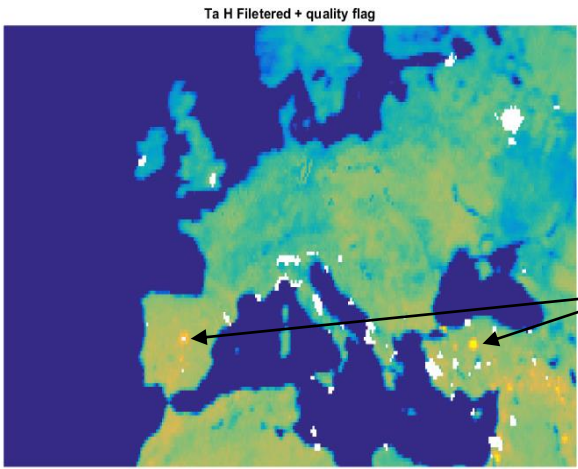
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Results in DoS

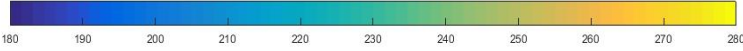


Low level



Residual
Courtesy A. Bringer, OSU

SUSMAI

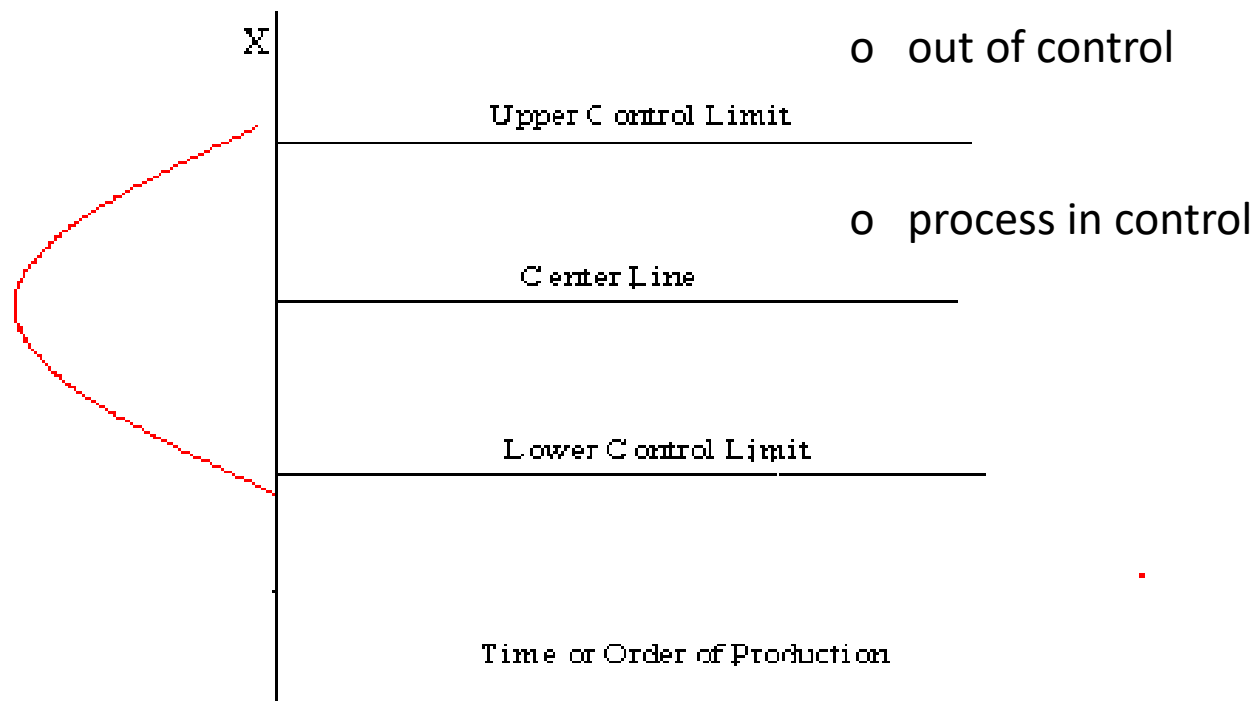




Control Charting for Process Monitoring

- Hypothesis: time series monitoring can reveal new sources or problematic sources that are not detected by current processes
- Borrow the classical “Shewhart *X-bar* and *s* Control Chart”
- ± 3 standard deviations

Theoretical Basis for a Control Chart



NIST/SEMATECH e-Handbook of Statistical Methods,
<http://www.itl.nist.gov/div898/handbook/pmc/pmc.htm>,
retrieved 9/20/17.

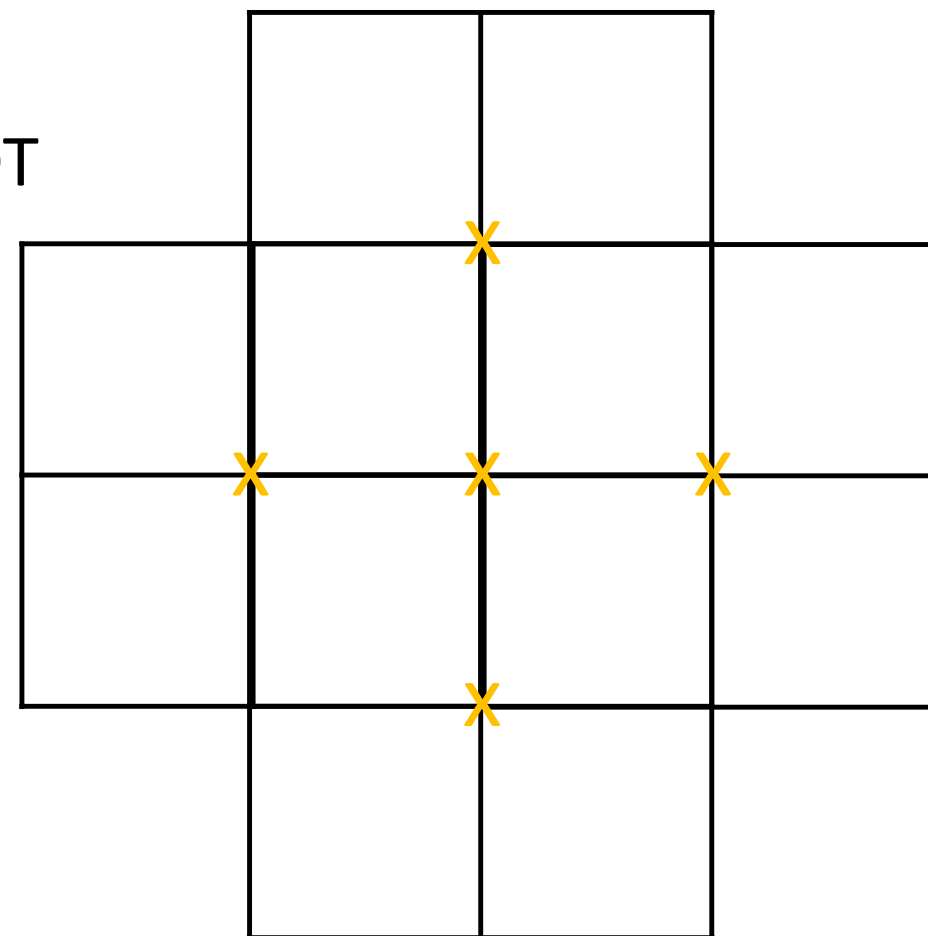


Data Preparation



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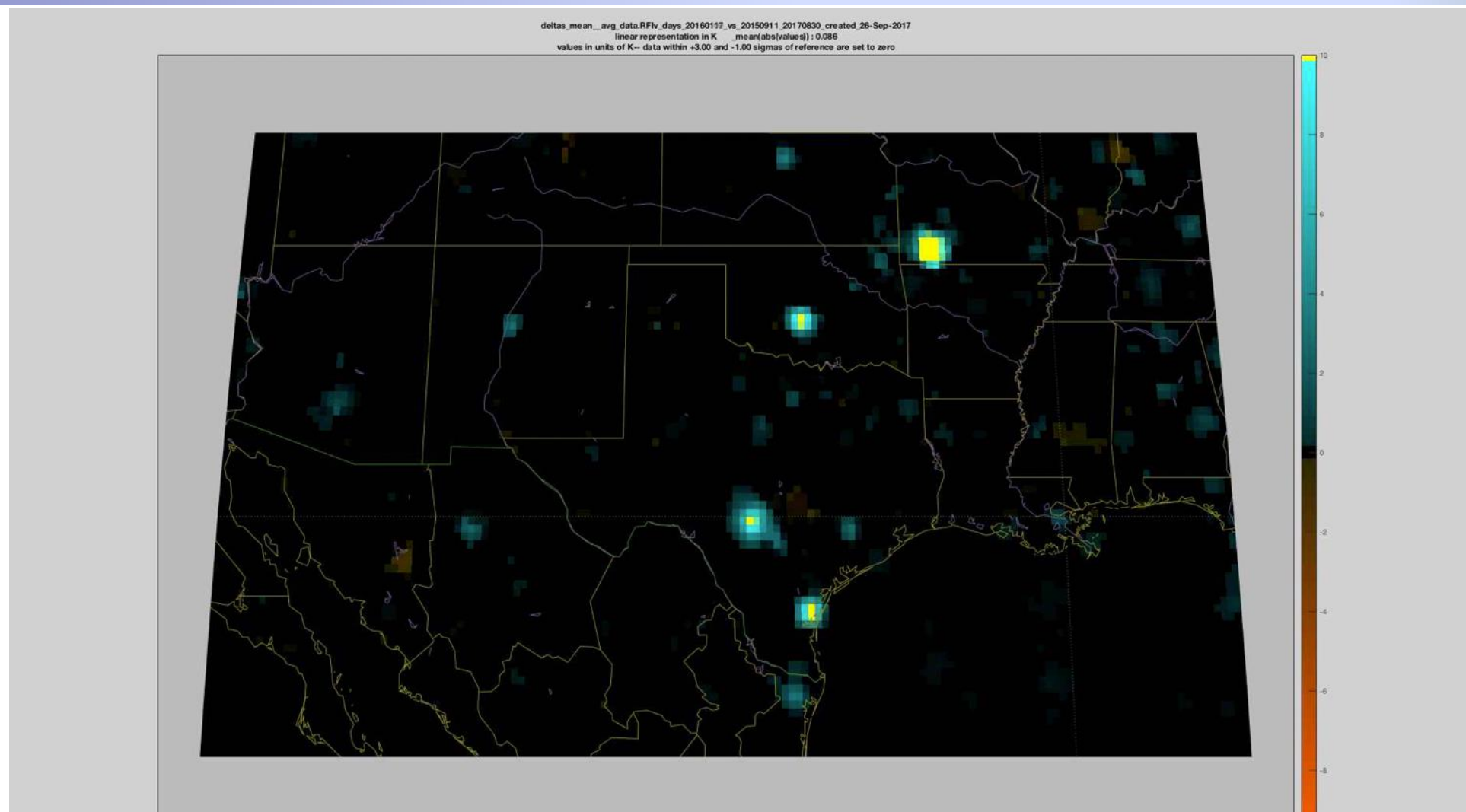
- 0.4-degree bins posted on 0.2 degree grid
- 8-day orbit cycle statistics computed in bin
- Mean, std, min, max of T_A , RFI intensity, NEDT
- September 2015 to August 2017



- Create geographic “control charts”



Case #1: Kerrville, TX

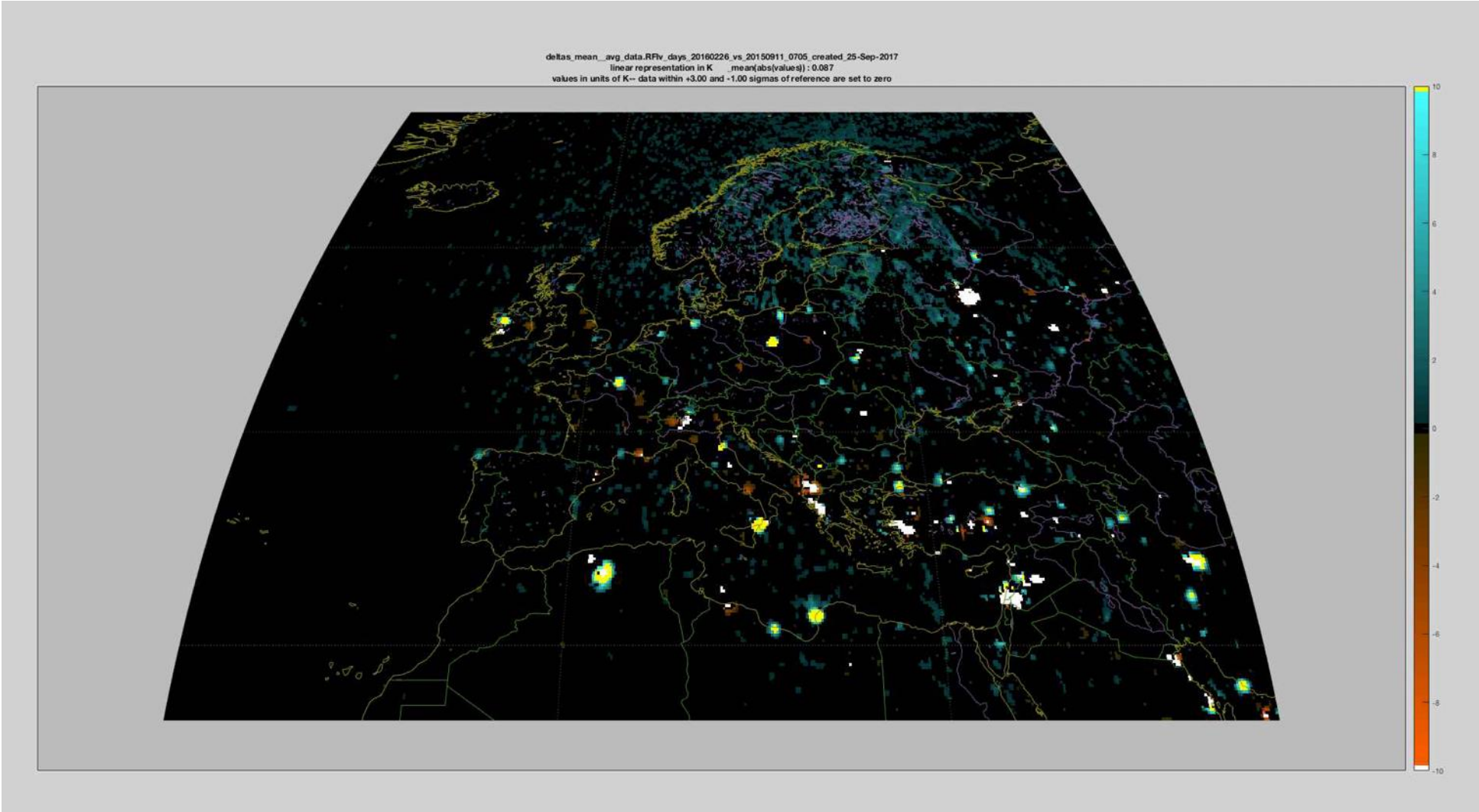




Case #2: Europe

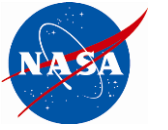


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What's next?



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- Current state:
 - Project/ST automate monitoring and geolocation tool
- SUSMAP Plan
 - Target low-level RFI: push the wall to the left
 - Binning of RFICAL file data
 - Kurtosis, spectrograms, detection flags
 - Data prior to application of filtering algorithms
 - Research feature vector composition
 - Research utility of classification using feature vectors
 - Test change detection using different norms
- What's most important for SMAP L2/3 users?